

# Fixed Points On Two Classes Of Finite Groups

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**Abstract.** The  $NG$ -groups are groups which consisting of transformations on a non-empty set  $A$  and have no bijection as its elements. In this paper, we consider the  $NG$ -groups by using fixed points.

**Keywords:** Finite groups, Symmetric groups, Fixed points.

## INTRODUCTION

We consider the  $NG$ -group which consisting of transformations on a non-empty set  $A$  and the group has no bijection as its element. Recall a permutation group on  $A$  is a group consisting of bijections from  $A$  to  $A$  with respect to compositions of mappings [2],[3]. It is well known that any permutation group on a set  $A$  with carnality  $n$  has order not greater than  $n!$ [4],[5]. There are some authors, [6], [7], Problem 1.4 in [1], considering groups which consists of non-bijective transformations on  $A$  where the binary operation is the composition of mappings. Our result is on the orders of such groups are mapping on a non-empty set  $A$  with respect to function compositions which are not subsets of symmetric groups by using the fixed points.

**PROPOSITION 1.1.** The maximal of maximum of  $NG$  has  $n \geq 3$  elements is  $(n - 1) \times n$ .

i.e.  $NG_{Max} = (n - 1) \times n$ .

**THEOREM 1.2.** Suppose  $NG$  a group which consists of non-bijective transformations on a non-empty set  $A$ . For any fixed point  $i \in A$ ,

$$|NG_i| \times |i^{NG}| = |NG|.$$

**REMARK 1.1.** The Theorem 1.1 is work for only if  $a \in A$  is a fixed point

## NG-Groups

In his section, we consider some examples of **NG**-groups which consisting of transformations on a non-empty set  $A$ .

**Definition 2.1.** The **NG**-groups are groups which consisting of transformations on a non-empty set  $A$  and the groups have no bijection as its elements.

**Definition 2.2.** Let  $f$  be a transformation mapping on  $A$ . An elements  $a$  is a **fixed** point if  $f(a) = a$ , otherwise it's a **moved** point. And, for  $g \in \mathbf{NG}$ ,  $fix(g)$  is the **number of fixed points**

$a \in A$  such that  $ag = a$

i.e.  $fix(a) =$  the number of fixed points of  $a \in A$ .

**Example 2.1.** Consider the set  $A = \{1, 2, 3\}$ , there are 27 transformations mappings from  $A$  to  $A$ . We know the symmetric groups of  $A$  is  $S_3$ :

$S_3 = \{(1, 2, 3), (2, 3, 1), (3, 1, 2), (1, 3, 2), (3, 2, 1), (2, 1, 3)\}$ .

So,  $S_3$  is a group. But, it is not an abelian group.

Moreover, there exists some groups that are subsets of  $Trans(a)$ , but not subsets of the  $Sym(a)$ . We know, every group must contain the identity element. From this point, we will choose an element of  $Trans(a)$  to be the identity element. We repeat this method for all elements of  $Trans(a)$ . In addition, we will find all groups that cannot be subset of the symmetric group  $S_3$ . For all elements of  $Trans(a)$ , we introduce the elements of  $Trans(a)$  as:

$\{(1, 1, 1), (1, 1, 2), (1, 1, 3), (1, 2, 1), (1, 2, 2), (1, 2, 3), (1, 3, 1), (1, 3, 2), (1, 3, 3),$   
 $(2, 1, 1), (2, 1, 2), (2, 1, 3), (2, 2, 1), (2, 2, 2), (2, 2, 3), (2, 3, 1), (2, 3, 2), (2, 3, 3),$   
 $(3, 1, 1), (3, 1, 2), (3, 1, 3), (3, 2, 1), (3, 2, 2), (3, 2, 3), (3, 3, 1), (3, 3, 2), (3, 3, 3)\}$ .

The groups of order 2 are:

$\mathbf{NG}_1 = \{(1, 1, 3), (3, 3, 1)\}$ ,  $\mathbf{NG}_2 = \{(1, 2, 1), (2, 1, 2)\}$ ,  
 $\mathbf{NG}_3 = \{(1, 2, 2), (2, 1, 1)\}$ ,  $\mathbf{NG}_4 = \{(1, 2, 3), (1, 3, 2)\}$ ,  $\mathbf{NG}_5 = \{(1, 2, 3), (2, 1, 3)\}$ ,  
 $\mathbf{NG}_6 = \{(1, 2, 3), (3, 2, 1)\}$ ,  $\mathbf{NG}_7 = \{(1, 3, 3), (3, 1, 1)\}$ ,  $\mathbf{NG}_8 = \{(2, 2, 3), (3, 3, 2)\}$ ,  
 and  $\mathbf{NG}_9 = \{(2, 3, 2), (3, 2, 3)\}$ . But,  $\mathbf{NG}_4 = \{(1, 2, 3), (1, 3, 2)\}$ ,  $\mathbf{NG}_5 = \{(1, 2, 3),$   
 $(2, 1, 3)\}$ , and  $\mathbf{NG}_6 = \{(1, 2, 3), (3, 2, 1)\}$  are subsets of  $Sym(A)$ .

The only groups of mapping on a set  $A$  with respect to function compositions which are not subsets of symmetric groups are:  $\mathbf{NG}_1 = \{(1, 1, 3), (3, 3, 1)\}$ ,  $\mathbf{NG}_2 = \{(1, 2, 1),$   
 $(2, 1, 2)\}$ ,  $\mathbf{NG}_3 = \{(1, 2, 2), (2, 1, 1)\}$ ,  $\mathbf{NG}_7 = \{(1, 3, 3), (3, 1, 1)\}$ ,  $\mathbf{NG}_8 = \{(2, 2, 3),$   
 $(3, 3, 2)\}$ , and  $\mathbf{NG}_9 = \{(2, 3, 2), (3, 2, 3)\}$ . And, the groups of order 3 are:  
 $\{(1, 2, 3), (2, 3, 1), (3, 1, 2)\}$  which is subset of  $Sym(A)$ .

Moreover, there are no groups of order greater than order 3 that cannot be subset of  $Sym(A)$ .

So, the only groups of mapping on a set  $A$  with respect to function compositions that cannot be subsets of symmetric groups are six groups of order 2;

$$NG_1 = \{(1, 1, 3), (3, 3, 1)\}, NG_2 = \{(1, 2, 1), (2, 1, 2)\}, NG_3 = \{(1, 2, 2), (2, 1, 1)\},$$

$$NG_7 = \{(1, 3, 3), (3, 1, 1)\}, NG_8 = \{(2, 2, 3), (3, 3, 2)\}, NG_9 = \{(2, 3, 2), (3, 2, 3)\}.$$

We can see, if  $A = \{a, b, c\}$ ,  $G = \{e, f\} \subset A^A$ .

Where  $e(a) = a, e(b) = a, e(c) = c, f(a) = c, f(b) = c, f(c) = a$ , we get:

$$NG_1 = \{e(a, b, c) = (a, a, c), f(a, b, c) = (c, c, a)\};$$

Where  $e(a) = a, e(b) = c, e(c) = c, f(a) = c, f(b) = a, f(c) = a$ , we get:

$$NG_7 = \{e(a, b, c) = (a, c, c), f(a, b, c) = (c, a, a)\};$$

Where  $e(a) = a, e(b) = b, e(c) = b, f(a) = b, f(b) = b, f(c) = a$ , we get:

$$NG_3 = \{e(a, b, c) = (a, b, b), f(a, b, c) = (b, a, a)\};$$

Where  $e(a) = b, e(b) = b, e(c) = c, f(a) = c, f(b) = c, f(c) = b$ , we get:

$$NG_8 = \{e(a, b, c) = (b, b, c), g(a, b, c) = (c, c, b)\};$$

Where  $e(a) = a, e(b) = b, e(c) = a, f(a) = b, f(b) = a, f(c) = b$ , we get:

$$NG_2 = \{e(a, b, c) = (a, b, a), f(a, b, c) = (b, a, b)\};$$

Where  $e(a) = b, e(b) = c, e(c) = b, f(a) = c, f(b) = b, f(c) = c$ , we get:

$$NG_9 = \{e(a, b, c) = (b, c, b), f(a, b, c) = (c, b, c)\}.$$

So, if  $A = \{a, b, c\}$ ,  $G = \{e, f\} \subset AA$ , we see  $e^2 = e, ef = fe = f, f^2 = e$ .

**Example 2.2.** Suppose  $A = \{1, 2, 3\}$ . Consider the transformation mapping on  $A$ .

$$f = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 1 & 3 \end{pmatrix}$$

It has two fixed points  $\{1, 3\}$  since  $f(1) = 1$  and  $f(3) = 3$ . And  $2 \in A$  is a movement point because  $f(2) \neq 2$ . The number of fixed points in  $NG$  is  $|fix(f)| = 2$  and the number of movement points is  $|Move(f)| = 1$ .

i.e. we have two fixed points and one movement point and one movement point.

Suppose  $m$  is a movement point in  $NG = \{e, f\}$  where  $e = (1, 2, m)$ .

If  $m = 1$ , we get  $NG_2$  and if  $m = 2$ , we get  $NG_3$ . Moreover,  $f$  not has a fixed point. Also, the point 3 is not a loop.

Where  $e = (1, m, 3)$ , then  $m$  can be 1 or 3.

If  $m = 1$ , then we get  $NG_1$  and if  $m = 3$ , then we get  $NG_7$ . An addition,  $f$  does not have fixed points and 2 not loop.

If  $e = (m, 2, 3)$ , then  $m$  can be 2 or 3.

If  $m = 2$ , we get  $NG_8$ . If  $m = 3$ , then we get  $NG_6$ . Moreover,  $f$  not have fixed points and 1 not a loop.

Now, we can generalization our result for a finite set  $A$ . For a finite set  $A$ , the identity could be  $e = (1, 2, \dots, n-1, m)$ . So, we have  $n-1$  possibility of  $m$ , where  $m = 1, 2, 3, \dots, n-1$ . So, we can get the numbers of maximum groups of  $NG$ , we denoted by  $NG_{Max}$ , of  $G$  that are mapping on a set  $A$  with respect to function compositions which are not subsets of symmetric groups by using the fixed points.

The number of maximum of  $NG$  which has  $n \geq 3$  elements is:

$$NG_{Max} = (n-1) \times \left( \frac{n!}{(n-1)! \times 1!} \right)$$

it means

$$NG_{Max} = (n-1) \times n$$

We can introduce the easy proposition **Proposition 2.1**. The maximal of maximum of  $NG$  which has  $n$  elements is

$$(n - 1) \times n, \text{ where } n \geq 3 .$$

$$\text{i.e. } |NG_{\text{Max}}| = (n - 1) \times n.$$

**Proof.** It easy to prove it by mathematical induction.

We will rewrite the definition of stabilizer of a point as an algebraic concept: it is the set of group elements which fix the point.

**Definition 2.3.** Let  $NG$  be a group which consists of non-bijective transformations on a non-empty set  $A$ . Suppose  $a$  be an element of  $A$ . Then

$$Stab(a) = NG_a = \{g \in NG : g.a = a\}$$

is called the stabilizer of  $a$  and consists of all the transformation  $NG$  that produce group fixed points in  $A$ .

i.e., that send  $a$  to itself.

Let  $NG$  be a group which consists of non-bijective transformations on a non-empty set  $A$ . If  $a \in A$ , then the point-stabilizer  $NG_a$  is the subgroup of  $NG$  formed by the elements which  $fix(a)$ . Moreover, we will write the definition of orbit of a point as a geometric concept: it is the set of places where the point can be moved by the group action and the size of an orbit as its length.

**Definition 2.4.** Let  $NG$  be a group which consists of non-bijective transformations on a non-empty set  $A$ . Suppose  $a$  be an element of  $A$ . Then, the group  $NG$  containing  $a \in A$  is

$$I^{NG} = Orb(a) = \{ag : g \in NG\}. \text{ And, we called it the } \mathbf{orbit} \text{ of } a.$$

Let  $NG$  be a group which consists of non-bijective transformations on a non-empty set  $A$ . If  $a \in A$ , then the orbit of  $a$  is the subgroup of  $A$  formed by the elements which  $fix(a)$ .

**Example 2.3.** Let  $A = \{1, 2, 3\}$  and  $NG = \{(1, 1, 3), (3, 3, 1)\}$ . So, the fixed points are  $\{1, 3\}$ . The group  $NG$  containing  $1 \in A$  is

$$1^{NG} = \{ig : g \in NG\} = \{1, 3\} = 2^{NG} = 3^{NG}.$$

The Stabilizer in a group  $NG$  of  $i$  is  $NG_i = \{g \in NG : ig = i\}$ .

$$NG_1 = \{(1, 1, 3)\}.$$

Note that,  $|NG_1| \times |1^{NG}| = 1 \times 2 = 2 = |NG|$ .

**Remark 2.1.** In previous example, if we take  $i = 2$ , then  $NG_2 = \varphi$ .

So,  $|NG_2| \times |2^{NG}| = 0 \times 2 \neq |NG|$ .

**Proposition 2.2.** Suppose  $NG$  a group which consists of non-bijective transformations on a non-empty set  $A$ . For any fixed point  $i \in A$ ,

$$|NG_i| \times |i^{NG}| = |NG|$$

**Proof.** Suppose  $i^{NG} = \{i1, \dots, ir\}$  and  $K = NG^i = \{k1, \dots, Km\}$ .

Choose elements  $g1 = 1, g2, \dots, gr$  such that  $igj = ij$  for each  $j$ .

Construct (some of) the group elements like this .

$k1g1 \ k1g2 \ \dots \ k1gr$

$k2g1 \ k2g2 \ \dots \ k2gr$

.....

.....

.....

$ksg1 \ ksg2 \ \dots \ ksgr$

□

The column  $j$  has elements form the coset  $Kgj$ .

In coset  $Kgj$ , every element maps  $i$  to  $ij$ .

So, this array contains exactly  $r \times s$  distinct elements of  $NG$ .

Now, we claim every element  $g \in NG$  as exactly once in array above.

We can find  $ig$ . By definition of fixed points and orbit  $ig \in i^{NG}$ . So,  $ig = ij$  for some  $j$ .

Calculate  $k := gg^{-1}$ . Then  $K$  is map from  $i$  to  $i$ .

So,  $k \in K = NG_1$ . Hence  $g = kgj$  lies in column  $j$ .

Counting:  $|NG| =$  number of elements in the array

$$= r \times s = |i^{NG}| \times |NG_i|$$

where  $|i^{NG}|$  as the length of  $i^{NG}$ .

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